Lzz 2/2 = (2py - 4px) 2-2 (2py - 1px) f $[[-2,2e]=[2p_y-yp_x,x]=[2p_y,x]-[yp_x,x]$ $= 2 \left[p_y, x \right] + \left[x, x \right] p_y - y \left[p_x, x \right] - \left[y, x \right] p_x$ = 0 + 0 - y(-iR) - 0= -i k y $[[1], y] = [2p_y - yp_{x}, y] = [2p_y, y] - [yp_{x}, y]$ $= 2 \left[\sum_{y,y} + \sum_{x} y \right] + \sum_{x} y \right] - \sum_{y} y \left[\sum_{x} y \right] - \sum_{y} y \right] p_{x}$ $= -i d_{x}$ $[[L_{\chi}, \chi] = [[x_{p_{\chi}} - y_{p_{\alpha}}, \chi] = [[x_{p_{\chi}}, \chi] - [[y_{p_{\alpha}}, \chi] = 0]$ $[[x,p_x] = [xp_y - yp_x, p_x] = [xp_y, p_x] - [yp_x, p_x]$ = 2 [py, pa] + [a, pe] py - 0 ilpy $[[x,p_y] = [[xp_y-yp_x,p_y] = [xp_y,p_y]-[yp_x,p_y]$ $= 0 - y [p_x, p_y] - [y_i p_y] p_x$ $[[2,p_2] = [2p_1,p_2] - [yp_2,p_2] = 0 - 0 = 0$ [[Lz, Lz] = [2py - 4pz)4pz - 2py] $= \left[\frac{2p_y}{yp_x} - \frac{1}{2p_y} \right] - \left[\frac{yp_x}{yp_x} - \frac{1}{2p_y} \right]$ = [L2, 1/p2-2py] = [L2, 4P2] - [L2, 2Py] = [[2x,y]px + y[[2x,p2] - [[2x,2]py - 2[2x,py] $= -i \mathcal{L} x p_2 + 0 - 0$ + 2 it pa $= i \mathcal{L} \left(2 p_{x} - 2 p_{x} \right)$ = it Ly $() \qquad \qquad (L\chi, \gamma^2) = [L\chi, \chi^2] + [L\chi, \chi^2] + [L\chi, \chi^2]$ - Rity + ityr - yithr - itrry + 0+0 [Lz, p] = [Lz, pz]pe +p[Lz, pz]+[Lz, py]py+py[lx, py] +pz[z,pz]+[kz,pz]pz = itpype + Paitpy - itpapy - pyith pat 0+0

Exercise 4.22

a) (By permutating x, y, z in question c) it follows that all components of \angle commute with p^2 and r^2 .

= 0

as $H = \frac{p^2}{2m} + V(r)$ = $\frac{p^2}{2m} + V(\sqrt{r^2})$, Horly departs on p^2 and r^2 , and thus H commutes with L